

Praktikum Autonome Systeme

An Introduction to Autonomous Systems

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→ Autonomous Systems

Definition: A system, which can operate without human intervention.

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3

(Possible) Real-World Applications

Smart Grids / Cities



Intelligent / Mobile Networks



Industry 4.0

Robotics



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Properties of Autonomous Systems

- Self-CHOP
 - Self-Configuration
 - Self-Healing
 - Self-Optimization
 - Self-Protection
- More Self-Properties
 - Self-Learning
 - Self-Organization
 - Self-Regulation



M. Salehie and L. Tahvildari, Autonomic Computing: Emergent Trends and Open Problems, ACM SIGSOFT Software Engineering Notes, 2005

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5

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6

Challenges of Autonomous Systems

- Dynamic Environments
- High Complexity
- Many Constraints:
 - Perception
 - Computational and Memory Resources
 - Energy Consumption
 - Communication
- Safety and Risk
- Security
- Quality Management







→ Artificial Intelligence

Why Artificial Intelligence?

AlphaGo (Zero)



https://deepmind.com/research/case-studies/alphago-the-story-so-far

OpenAl Five



https://openai.com/blog/openai-five/

AlphaStar



https://deepmind.com/blog/article/alphastar-mastering-real-timestrategy-game-starcraft-ii

Walking Robot



https://bair.berkeley.edu/blog/2018/12/14/sac/

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Machine Learning

- **Goal:** Create programs that learn how to solve complex problems
- Learn statistical models from experience / data



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Why Machine Learning?

- **Goal:** Create programs that learn how to solve complex problems
- Many problems cannot be solved by engineering handcrafted solutions
 - Too many aspects to consider
- Too many rules
 Hard adaption to changes
 Hard generalization
 Example:
 How to classify a star?
 Has five corners?



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Types of Machine Learning



Unsupervised Learning

Supervised Learning

Reinforcement Learning



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Challenges of Machine Learning

- Data Availability
- Data Complexity
- Efficiency
- Compactness
- Interpretability
- Robustness
- Adaptivity



Automated Planning

- **Goal:** Find (near-)optimal strategies to solve complex problems
- Use (heuristic) lookahead search on a **given model** of the problem



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Why Automated Planning?

• **Goal:** Find (near-)optimal strategies to solve complex problems

- Planning is necessary, if **explicit reasoning** is required:
 - Consideration of risks and uncertainties
 - Consideration of hard constraints
- Planning is **flexible**:
 - Use the same method for different problems by replacing the model
 - Search for multiple alternative strategies





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Planning Approaches (Examples)



Tree Search

Evolutionary Computation

Dynamic Programming



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Challenges of Automated Planning

- Model Availability
- Model Uncertainty
- Computational and Memory Efficiency
- Real-time Planning



→ Decision Making

Decision Making

- **Goal:** Autonomously select actions to solve a (complex) task
 - time could be important (but not necessarily)
 - maximize the expected reward for each state







- Consider a situation, where you have to make a choice
- **Example:** What are you going to do after this lecture?





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Multi-Armed Bandits

- Multi-Armed Bandit: situation, where you have to <u>learn</u> how to make a good (long-term) <u>choice</u>
- Explore choices to gather information (= Exploration)
 - Example: random choice
- **Prefer** promising choices (= Exploitation)
 - Example: greedy choice (e.g., using argmax)

 A good Multi-Armed Bandit solution should always balance between Exploration and Exploitation







Decision Making Challenges and Outlook

- Sequential Decision Making
- Problem Complexity
- Sparse/Delayed Feedback
- Sample Efficiency
- Uncertainty



Thank you!